

Depth
Onboard
Processing



SDK
Win/Linux/
ROS/Android







Measurement Range 0.4~8.0 m



3D Accuracy
Millimeter

Overview

HIFLY's 3D smart camera uses innovative active stereo vision technology with core patents to obtain more depth details and more robust environmental adaptability than traditional binocular vision.

HF-815-E1 combines the structured light with the mature RGB sensor technology to provide real-time RGB and depth images.

With reliable measurement results and the aluminum alloy body, HF-815-E1 becomes an ideal solution for robotics, logistics, inspection and other applications.

Advantages

HF-815-E1 includes two infrared (IR) sensors, one RGB sensor and several structured-light projectors. Comparing to the traditional binocular cameras, HF-815-E1 provides:

- More depth details
- + More robust to ambient light interference

Industrial Sensor

HF-815-E1 is splash, water, and dust resistant and has been tested under controlled laboratory conditions with a rating of IP65 under IEC standard 60529.

Trigger Mode

HF-815-E1 supports the software and hardware trigger. The customers can synchronize multi-cameras to capture images with the hardware trigger.

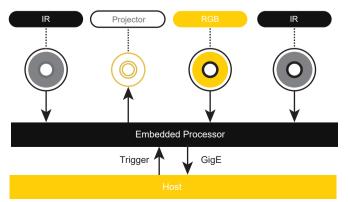
High Accuracy

With the innovative multi-laser projecting system and compact package size, HF-815-E1 provides high measurement accuracy in its large working range and wide FOV.

Note

All cameras have been calibrated with intrinsic parameters before delivery. If you need to calibrate multiple cameras with extrinsic parameters, please contactHIFLY technical support.

Principle



Structured-light Projector

Project the structured light to objects for assisting the active stereo system to calculate depth data.

Infrared Sensor

Receive the structured light reflected from the objects surface.

RGB Sensor

Capture RGB images.

Embedded Processor

Process infrared and RGB images:

- Calculate depth data and achieve alignment and synchronization with RGB images.
- Upload data through Gigabit Ethernet (GigE).
- Receive trigger signal from the host or the hardware trigger source.

Applications











Integrity Check

3D Content Generation

Palletizing / De-palletizing

Static Volume Measurement

Industrial Sorting

Features

Dimensions&Weight		
L x H x W (excluding interfaces)	145.0 mm × 35.0 mm × 90.0 mm	
Weight	620 g	

Measurement	
Measurement range(mm)	400 ~ 8000
FOV (H/V)	60°/48°
Z Accuracy(mm)	0.68mm@800mm
X/Y Accuracy(mm)	3.2mm@1000mm

Software	
OS	Linux/Windows/ROS/Android
Development platform	Percipio Camport SDK
API	C/C++、C#、Python、Java

Electronics		
Supply voltage	DC 24V; IEEE802.3at/af POE	
Power consumption (idle)	5.0 W	
Power consumption (continuous)	11.3 W	

Note:

The specs and dimension may change without notice.

Performance	
Depth	5 fps @ 1280×960
	5 fps @ 640×480
	5 fps @ 320×240
	4 fps @ 2560 x 1920 @ YUYV
	7 fps @ 1920 x 1440 @ YUYV
RGB	16 fps @ 1280 x 960 @ YUYV
	30 fps @ 640 x 480 @ YUYV
	6 fps @ 2560 x 1920 @ CSI BAYER12GBRG

	Point cloud,	donth	infrared	and PCP	images
Output data	r on it cloud,	uepui,	IIIIIaicu	and NGL	iiiiaycs

Interface	
Power&Trigger	8-pin aviation plug
Ethernet	M12 X-Coding

Ambient Data	
Operating temperature	-10°C ~ 50°C
Storage temperature	-20°C ~ 55°C
Enclosure rating	IP 65

