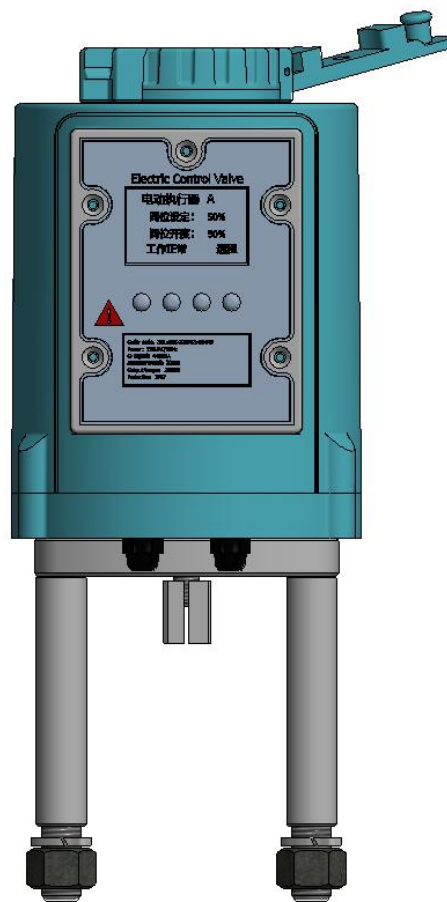


XSL-5XX Series

Linear Electric Actuator

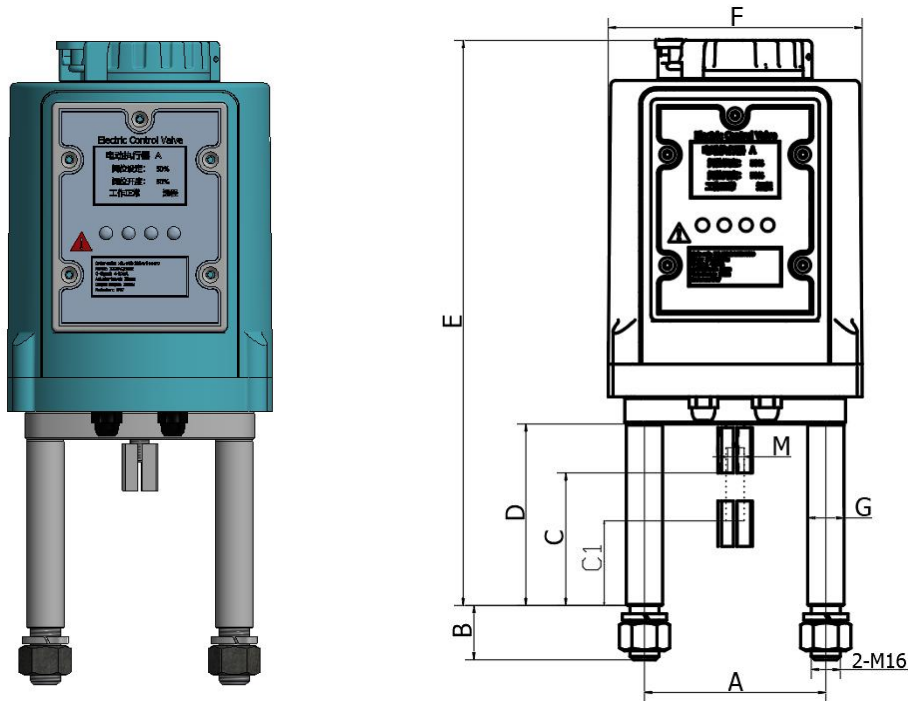
Instruction Manual



1、Product Overview

XSL-5XX series electric actuators, part of the DDZ electric unit combination instruments, function alongside regulating valve bodies to form electric regulating valves extensively used in industrial process measurement and control systems. These actuators are applicable across various sectors including petroleum, chemical, water treatment, maritime, papermaking, power generation, heating, building automation, and light industry. Compatible with both 24VAC (or 220VAC) AC and 24VDC DC power supplies, they respond to 4-20mA or 0-10V DC control signals to precisely position valves, facilitating automated control.

2、Dimensions



| MODEL | Dimensions | | | | | | |
|-------------------------------------------------------------------------------------------------|------------|----|-----|----|-----|-----|-----|
| | A | B | C | C1 | D | E | F |
| XSL502 | 100 | 30 | 100 | 60 | 110 | 311 | 140 |
| XSL504 | | | | | | | 140 |
| <p>Note: Point C is the highest when fully open; C1 is the lowest when fully closed.</p> | | | | | | | |

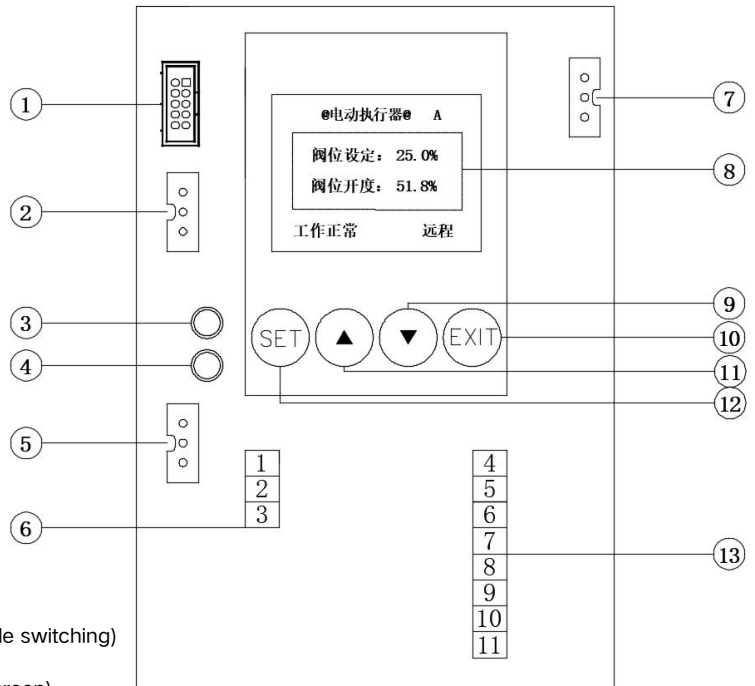
3、Specifications

| MODEL | XSL-502 | XSL-504 |
|-------------------------|---------------------------------------------------------------------------------------------------------------------------|---------|
| Input Voltage | AC: 220V/50Hz、24V/50Hz; DC: 24V; | |
| Input Signal | 4-20mA、0-10V | |
| Feedback Signal | 4-20mA、0-10V | |
| Communication Interface | RS485 MODBUS protocol | |
| Power Consumption VA | 12 | 18 |
| Thrust kN | 2 | 4 |
| Stroke mm | 20 | 40 |
| Torque Protection | Yes | |
| Manual override | Yes | |
| Protection Rate | IP67 | |
| Remote Control | Optional | |
| Speed s/mm | 1.4; 3 | |
| Cable Interface | 2- M14*1.5 | |
| Control Accuracy | 0.0% ~ ±5% (Note: Values may vary with installation conditions and is expressed as a percentage of the rated stroke.) | |
| Hysteresis Adjustment | 0.1% ~ 5.0% | |
| Ambient Temperature | -20°C ~ 60°C (special mention required for use within -45°C to -20°C) | |
| Weight | 2.8 kg | 2.8 kg |

4、Electrical Wiring

4.1 Wiring Diagram

- 1、 Drive Communication Interface
- 2、 Sensor Interface
- 3、 Actuator Up Indicator
- 4、 Actuator Down Indicator
- 5、 Drive Power Interface
- 6、 Actuator Power Interface
- 7、 Mainboard 24VIN Power Interface:
- 8、 LCD Display
- 9、 Data "-" (also for local decrease operation)
- 10、 Menu Exit Button (also for "Local"/"Remote" mode switching)
- 11、 Data "+" (also for local increase operation, unlock screen)
- 12、 Parameter Setting Button (for menu navigation, selection, confirmation)
- 13、 Signal Input, Output, RS485 (customizable), Alarm Wiring Terminals

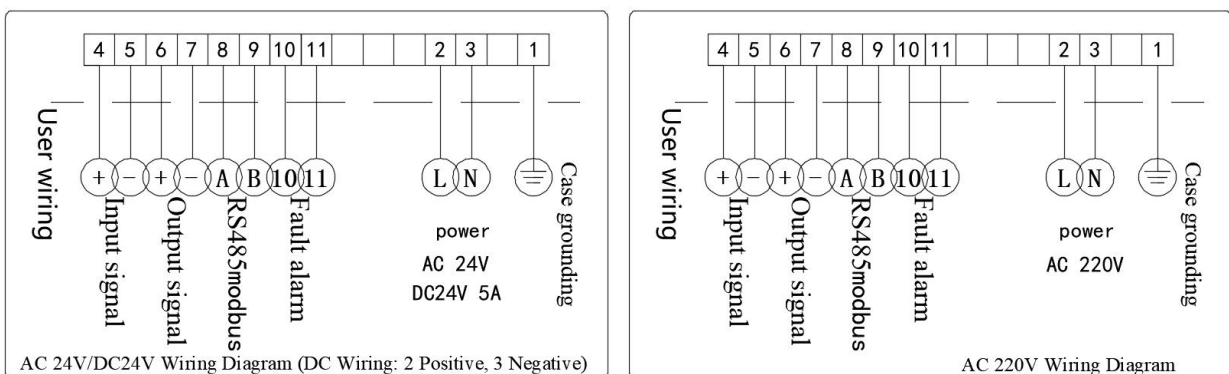


4.2 Wiring Guide (AC/DC Diagrams):

The actuator accepts analog inputs 4-20mA and 0-10V, including non-standard signals, with corresponding analog signal feedback. Digital 485 signals using MODBUS protocol require customization.

The default setup supports 4-20mA I/O. For additional signals, contact our sales department.

Note: Wiring functions can be combined as needed, and power specifications are adjustable.



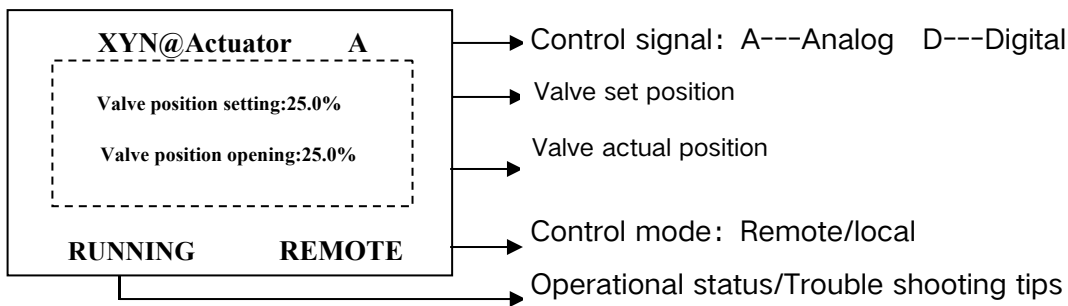
Note: Wiring functions can be combined as needed, and power specifications are adjustable.

5、Parameter Settings

Functions of Control Panel Buttons:

- “SET” Enter menu or confirm selections.
- “▲” Navigate to the previous menu item, increase input values, or unlock the screen.
- “▼” Navigate to the next menu item or decrease input values.
- “EXIT” Exit and return to the operational state or the previous menu level.

5.1 Normal Operation LCD Display



5.2 Menu Structure

| NO. | Main Menu | Submenu | Remarks |
|-----|------------------------------------|---------------------------------|----------------------------------------------------------------------------|
| 1 | 01-Device information | 01-NO. | Product factory identity |
| 2 | | 02-Hardware version | Control board hardware |
| 3 | | 03-Software version | Software version |
| 4 | | 04-Protocol version | Communication protocol version |
| 5 | 02-Valve position verification | 01-Automatic stroke calibration | Automatic adjustment of valve stroke |
| 6 | | 02-Stroke manual calibration | Manual adjustment of valve stroke |
| 7 | 03-Sensor calibration (Permission) | 01-Analog input checksum | The company's internal parameter debugging and testing are not open to the |
| 8 | | 02-Analog output check | |
| 9 | | 03-Valve position sensor | |

| | | | |
|----|------------------------------------------------------|------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------|
| | Control) | adjustment | public |
| 10 | | 04-TrvK_10mm/90° | |
| 11 | | 05-XYN_EEP_MAIN | |
| 12 | 04-Control performance (Permission Control) | 01-Cut on the stroke | Please read carefully: 7.3 stroke |
| 13 | | 02-Cut under stroke | limit and cutting under the parameter setting of electric actuator |
| 14 | | 03-Cut under stroke | Cut under stroke |
| 15 | | 04-Hysteresis error spread | Control accuracy |
| 16 | | 05-Motor reversal delay | Motor response signal change time |
| 17 | | 06-Flow characteristics | Valve flow control characteristics |
| 18 | | 07-Direction of action of the valve | Actuator off direction |
| 19 | | 08-Rated torque compensation | When the torque is low, a certain value can be modified to increase the torque |
| 20 | 05-Control signal(Permission Control) | 01-Control signal selection | You can set the control signal type |
| 21 | | 02-Restart the control mod | Please read carefully: 7.3 Valve |
| 22 | | 03-Upper limit of analog quantity | position setting control signal selection under electric actuator |
| 23 | | 04-Lower limit of analogue | parameter setting |
| 24 | | 05-Signal forward and negative action | Actuator modalities |
| 25 | | 06-Signal fault handling | Actuator state after signal breaking: hold, full on, full off, set; When selecting Settings, press the Settings button to enter the |

| | | | |
|----|------------------------------------------------|------------------------------------------|------------------------------------------------------------------------------------------------------------------------|
| | | | submenu to modify the fault handling location to be set |
| 26 | | 07-Signal fault detection enabled | |
| 27 | 06-Alarm parking settings (Permission Control) | 01-Handwheel switch enabled | Used to set whether to stop the actuator when a fault occurs, but the main interface will still prompt for the failure |
| 28 | | 02-Failure in the direction of operation | |
| 29 | | 03-Memory failure | |
| 30 | | 04-Valve stall failure | |
| 31 | | 05-Torque overload detection | |
| 32 | | 06-Motor overheating detection | |
| 33 | 07-LCD with communication | 01-- Backlight time | LCD screen constant light time adjustment |
| 34 | | 02-Grayscale settings | Sets the display font brightness |
| 35 | | 03-Auto lock screen | Protect the actuator from being operated by unrelated personnel |
| 36 | | 04-Lock screen password | Screen password unlock can be set |
| 37 | | 05-Permission password | You can set a password to lock the main menu |
| 38 | | 06-Local address | The specific model is valid |
| 39 | | 07-Communication baud rate | The specific model is valid |
| 40 | 08-Language | | Chinese/English option |

5.3 Parameter Settings

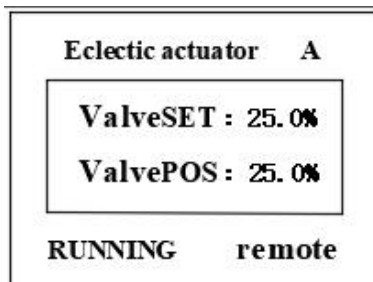
➤ *Accessing the Menu:*

Unlock the screen by pressing the "▲" button when locked.

During normal operation, press the "SET" button to enter the main menu. Navigate through 9 parameter setting functions using the "▼" or "▲" buttons, press "SET" to enter the selected submenu, and press "EXIT" to return to the previous menu. The operation in submenus is similar.

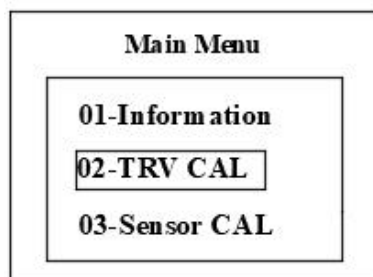
Local/Remote Switching:

Local/Remote Switching: In normal operation, press the "EXIT" button to toggle between "Local" and "Remote" control modes. In "Local" mode, the valve's current position can be adjusted using the "▼" or "▲" buttons. In "Remote" mode, the control signal source (analog signal 4~20mA, digital signal RS485, or other bus interfaces) sets the valve position, and the electric actuator then moves the valve to the corresponding position.

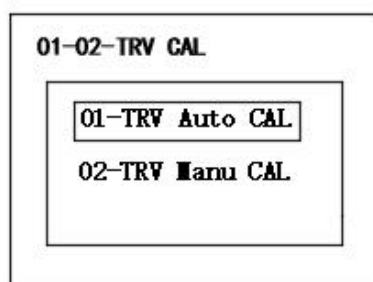


After the actuator and valve are installed, the correct power supply is applied, the valve stroke will be calibrated, and the set button will be pressed to enter the main menu.

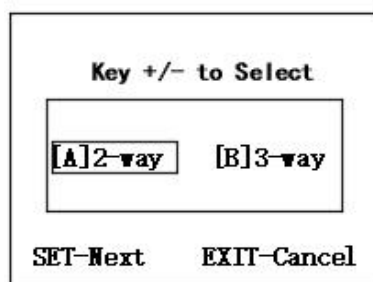
If you need to unlock the screen, press the [+ (Up) buttons to unlock the screen.



Press the setting button to enter the main menu, press the +/- button to select: 02-TRV CAL, press the Set button to enter.



Press the +/- buttons to select: 01 stroke automatic calibration, press the set button to enter.

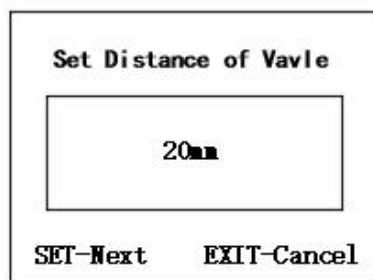


Press the +/- button to select the type of valve installed:

[A] 2-way: The valve closes as the actuator moves down.;

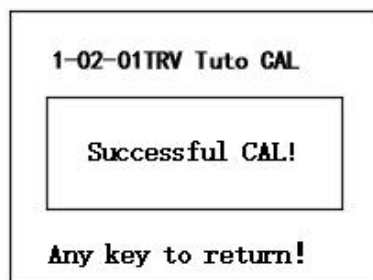
[B] 3-way : means that the valve is closed when the actuator runs up or down.

This step introduces the upper closing valve verification steps, press +/- to select [A] 2-way, press the set button to confirm.



Press the +/- button to set the valve stroke matched by the actuator, and press the set button to enter the next step of automatic valve position verification.

If [B] is selected, the 3-way valve will skip this step directly and perform automatic valve position verification.



The actuator appears in the calibration valve [stroke] The following steps will appear:

[Preparation];

[X11: Find the valve full closing point]; [X21: Look for the valve full

opening.]When [Calibration Completed] is displayed, the valve position

verification step is complete, press the exit button to return to the main interface.